

# CFD Theory

## Lecture 19



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## Outline

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Discretization Methods

Finite Difference Method

Explicit and Implicit

Conservation Form

# Discretization Methods

## Discretization Methods

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Finite Difference

Finite Volume

Finite Element

# Finite Difference Method

## Finite Difference

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Forward/Backwards difference

Central difference

Second derivative

# Non-equally spaced mesh

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Explicit and Implicit

# Explicit vs Implicit

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Consider a model equation like

$$\frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} = 0$$

(e.g., continuity where  $F = \rho u$  and  $G = \rho v$ )

**Explicit:** Vectorizable, easier to implement, but requires smaller step sizes for stability.

**Implicit:** Can take larger step sizes, but memory intensive.



# Conservation Form

## Conservation Form

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Euler equations in conservation form

$$\frac{\partial U}{\partial t} + \frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} + \frac{\partial H}{\partial z} + Q = 0$$

$$U = \begin{bmatrix} \rho \\ \rho u \\ \rho v \\ \rho w \\ e \end{bmatrix}$$

$$F = \begin{bmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ \rho uw \\ (e + p)u \end{bmatrix}$$

$$G = \begin{bmatrix} \rho v \\ \rho uv \\ \rho v^2 + p \\ \rho vw \\ (e + p)v \end{bmatrix}$$

$$H = \begin{bmatrix} \rho w \\ \rho uw \\ \rho vw \\ \rho w^2 + p \\ (e + p)w \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 \\ \rho f_x \\ \rho f_y \\ \rho f_z \\ p\dot{q} + \rho(u f_x + v f_y + w f_z) \end{bmatrix}$$